Low Voltage Power Supplies for SCT FE Electronics

Prague's group

SCT week 9–13 March,1998 Update: 20 March,1998

Abstract

In this note is described a present status of requirements to the attributes of the subsidiary system for SCT detector FE electronics and its behaviour in the operating conditions.

1 Introduction

The low voltage power supply system is a part of SCT detector system and provides the supply voltages, control voltages and control signals to a front-end electronics of the SCT detector modules and communicates with the SCT Detector Control System. The SCT system linkages are shown in Fig.1.

The LV power module is designed as a floating multi-voltage supply providing the set of six different voltages. In addition, two logical signal lines and four lines for remote sensing run from the power module to the FE electronics.

Power block consists of **four** power modules and is placed as an one slot unit in the crate. Power block controller (PBC) communicates with a control logic of each power module and with the crate controller. The hardware protection against over-voltage and over-current are schematically shown in Fig.2 and Fig.3.

2 Requirements

For complete design of the low voltage power supply system is necessary to define several groups of requirements:

- operating data
- control and monitoring
- hardware protection
- control lines
- interlocks
- environmental data

Present knowledge of this data is summarised in following tables (proposed values are shown in parenthesis):

OPERATING DATA:

	Analog	Control	Digital	2x LDC	supply
	voltage	VI1	voltage	voltages	PIN
$\operatorname{Parameter}$	supply	voltage	supply	$\operatorname{control}$	supply
Nominal	$3.50\mathrm{V}$	1.V	4.00V	1.6-6.6V	10V
(FE load on detector)					
	Max 5.50V	$2.0\mathrm{V}$	6.00V	$8.0\mathrm{V}$	$10.5\mathrm{V}$
Vout regulation					
	Min (3.00V)	$0.\mathrm{V}$	(3.50V)	1.0 V	(2.0V)
Output ripple	$35 \mathrm{mV}$	$10 \mathrm{mV}$	$35\mathrm{mV}$	$10 \mathrm{mV}$	$100 \mathrm{mV}$
(peak to peak)					
Over-voltage trip	$5.50\mathrm{V}$	(2.1V)	6.00V	(8.1V)	(11.0V)
Start value-hardwired	$3.50\mathrm{V}$	(1.V)	$4.00\mathrm{V}$	(4.0V)	(10V)
Normal turn ON					
Start ramping time	$(10 \mathrm{ms})$	$(10 \mathrm{ms})$	$(10 \mathrm{ms})$	$(10 \mathrm{ms})$	$(10 \mathrm{ms})$
Normal turn ON					
Stop ramping time	$1\mathrm{ms}$	$1\mathrm{ms}$	$1\mathrm{ms}$	$1\mathrm{ms}$	$1\mathrm{ms}$
Normal turn OFF					
Max current	0.9A	$6 \mathrm{mA}$	$0.26 \mathrm{A}$	$5 \mathrm{mA}$	$1 \mathrm{mA}$
Min current	?	0	?	?	?
Over-current trip	1.2A	$10 \mathrm{mA}$	0.3A	$10 \mathrm{mA}$	$2\mathrm{mA}$
Grounding	$\operatorname{RET1}$	$\operatorname{RET1}$	$\operatorname{RET2}$	$\operatorname{RET2}$	RET3

CONTROL AND MONITORING:

Voltage setting by	\mathbf{yes}	\mathbf{yes}	yes	yes	\mathbf{yes}
digital control input					
Voltage setting	$10\mathrm{mV}$	$10 \mathrm{mV}$	$10 \mathrm{mV}$	$100 \mathrm{mV}$	1V
$\operatorname{resolution}$					
Time for voltage	$100 \mathrm{ms}$	$100 \mathrm{ms}$	$100 \mathrm{ms}$	$100 \mathrm{ms}$	$100\mathrm{ms}$
$\operatorname{adjustment}$					
Remote sensing	yes	no	yes	no	no
and feedback control					
Vload monitoring	\mathbf{yes}	no	$_{\rm yes}$	no	no
remote sensing					
Module control logic	$2\mathrm{ms}$	$2\mathrm{ms}$	$2\mathrm{ms}$	$2\mathrm{ms}$	$2\mathrm{ms}$
time interval					
Over voltage, $Vout=0$	\mathbf{yes}	yes	$_{\rm yes}$	yes	$_{\rm yes}$
Digital control protection					
Over current	yes	yes (Vmin)	\mathbf{yes}	yes (Vmin)	yes(Vmin)
Status register (V&I)	\mathbf{yes}	yes	$_{\rm yes}$	yes	$_{\rm yes}$
Monitoring	V/I	V	V/I	V	V
Voltage monitoring	$5 \mathrm{mV}$	$5\mathrm{mV}$	$5 \mathrm{mV}$	$40\mathrm{mV}$	$40\mathrm{mV}$
accuracy					
Current monitoring	$1 \mathrm{mA}$	-	$1 \mathrm{mA}$	-	_
accuracy					
Internal monitoring	$500 \mathrm{Hz}$	$500\mathrm{Hz}$	500 Hz	$500 \mathrm{Hz}$	$500 \mathrm{Hz}$
frequency (PBC)					

HARDWARE PROTECTION:

Over-voltage	crow-bar	limit	crow-bar	limit	limit
Trip OFF	100 us	2 m s	$100\mathrm{us}$	$2\mathrm{ms}$	$2\mathrm{ms}$
Over-current	limit	limit	limit	limit	limit
Trip OFF	$2\mathrm{ms}$	$2\mathrm{ms}$	$2\mathrm{ms}$	$2\mathrm{ms}$	$2\mathrm{ms}$
Status register	yes	\mathbf{yes}	yes	yes	yes
latching the trip					
cause (V and I)					

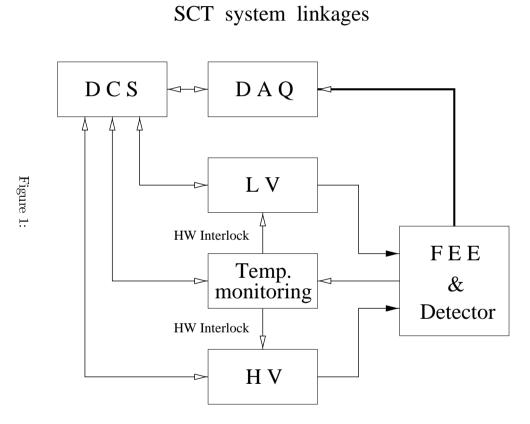
There is the parity control in PBC of the incoming information from each power module. In the case of "parity error" the power module is turned OFF.

LOW CURRENT CONTROL LINES:

- "Clkselect" and "Clkreset" (two lines per module). The levels are nominally: Lo=0V +/-1V, Hi=+4V +/-1V
- Four lines for remote sensing of analog (3.5V) and digital (4V) voltages.

INTERLOCKS:

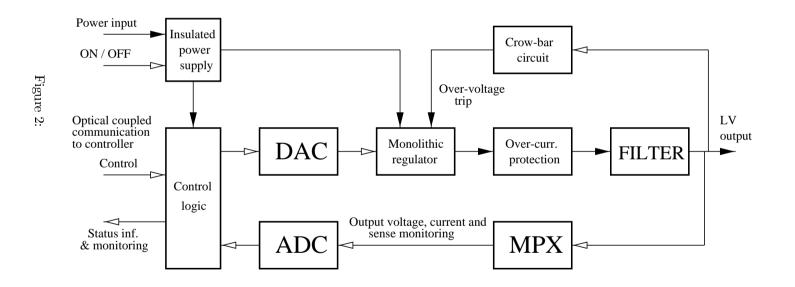
```
Interlock initiated by DCS:
        Modularity: power module
             Action power block controller turns OFF the power module
                     and sends its status information over the crate
                     controller to DCS.
           Restart: Normal turn ON (DCS initiates the set of Voper
                     values)
Hardwired interlock:
        Modularity: power block
             Action: hardwired logic turns OFF all six power modules
                     PBC confirms the "normal power modules OFF"
                     and sends the status information to DCS
                     (PBC stays ON for all time)
           Restart: Normal turn ON (DCS initiates the set of Voper
                     values)
Internal temperature interlock:
        Modularity: power block
             Action: power block controller turns OFF the power module
                     and sends its status information over the crate
                     controller to DCS.
           Restart: Normal turn ON (DCS initiates the set of Voper
                     values)
```





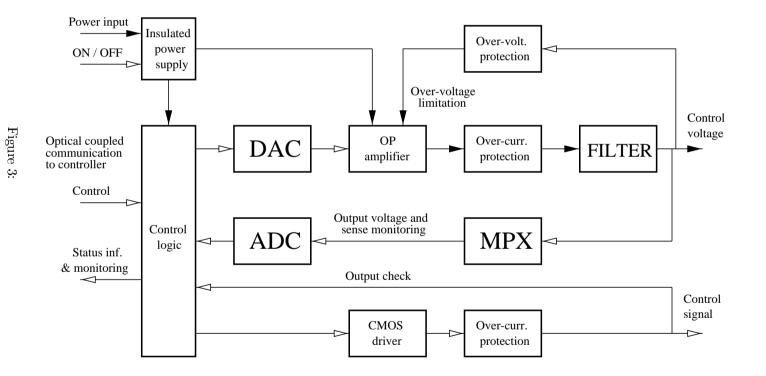
Radiation ?	Magnetic field 0 -	Electrical field	Rel.humidity (30	Temperature (10	
	0 - 1000 Gauss		(30 - 70%)	(10 - 40deg.C)	
(5*10^12 n/cm2 in ATLAS cavern)					

SCT low voltage power supply block diagram



СЛ

SCT FEE control voltage and signal block diagram



6